## iC-MFN

## FEATURES

- 8-fold level shift up to 40 V output voltage
- Inputs compatible with TTL and CMOS levels, 40 V voltage proof
- Level shift configurable to 5 V , 10 V or supply voltage
- Short-circuit-proof push-pull current sources for driving FETs slowly
- Safe low output state with single errors
- Ground and supply voltage monitor
- Status output for error and system diagnostics
- Temperature range from -40 to $125^{\circ} \mathrm{C}$
- Protective ESD circuitry


## APPLICATIONS

- Operation of N-FETs from 1.8 V , $2.5 \mathrm{~V}, 3.3 \mathrm{~V}$ or 5 V systems



## BLOCK DIAGRAM



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## DESCRIPTION

iC-MFN is a monolithically integrated, 8-channel level adjustment device which drives N -channel FETs. The internal circuit blocks have been designed in such a way that with single errors, such as open pins (VB, VBR, GND, GNDR) or the short-circuiting of two outputs, iC-MFN's output stages switch to a predefined, safe low state. Externally connected N channel FET are thus shut down safely in the event of a single error.

The inputs of the eight channels consist of a Schmitt trigger with a pull-down current source and are compatible with TTL and CMOS levels and are voltageproof up to 40 V . The eight channels have a currentlimited push-pull output stage and a pull-down resistor at the output. The hi-level at one of the inputs EN5, EN10 or ENFS defines the output hi-level and enables the outputs. The output hi-level is disabled with the lo-level at all inputs EN5, EN10 and ENFS or with the hi-level at more than one input.
iC-MFN monitors the supply voltage at VB and VBR pin and the voltages at the two ground pins GND and GNDR. Both power supply pins VB and VBR and both pins GND and GNDR must be connected together externally in order to guarantee the safe low state of the output stages in the event of error.

Should the supply voltage at VB undershoot a predefined threshold, the voltage monitor causes the out-
puts to be actively tied to GND via the lowside transistors. If the ground potential ceases to be applied to GND, the outputs are tied to GNDR by pull-down resistors.

If the connection between the ground potential and the GND pin is disrupted, the highside and lowside transistors of the output stages are shut down and the outputs tied to GNDR via the pull-down resistors. If on the other hand the connection between ground potential and the GNDR pin is disrupted, only the output stage highside transistors are shut down; the outputs are then actively tied to GND via the lowside transistors.

Pull-down currents provide the safe lo-level at open inputs IN1...8, EN5, EN10 and ENFS. The pulldown currents have two stages in order to minimize power dissipation with enhanced noise immunity.

The status of the device is indicated with the OpenDrain pin NOK and can be used for system diagnostics.

Temperature monitoring protects the device from too high power dissipation.

The device is protected against destruction by ESD.

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PACKAGES QFN24 $4 \mathrm{~mm} \times 4 \mathrm{~mm}$ to JEDEC

PIN CONFIGURATION QFN24
(top view)


## PIN FUNCTIONS

No. Name Function

| 1 | OUT1 | Output channel 1 |
| :--- | :--- | :--- |
| 2 | VB | Supply Voltage |
| 3 | VBR | Supply Voltage (R) |
| 4 | EN5 | Enable input hi-level $=5 \mathrm{~V}$ |
| 5 | EN10 | Enable input hi-level $=10 \mathrm{~V}$ |
| 6 | IN1 | Input channel 1 |
| 7 | IN2 | Input channel 2 |
| 8 | IN3 | Input channel 3 |
| 9 | IN4 | Input channel 4 |
| 10 | IN5 | Input channel 5 |
| 11 | IN6 | Input channel 6 |
| 12 | IN7 | Input channel 7 |
| 13 | IN8 | Input channel 8 |
| 14 | NOK | Output inverted status |
| 15 | ENFS | Enable input full scale hi-level = VB |
| 16 | GNDR | Ground (R) |
| 17 | GND | Ground |
| 18 | OUT8 | Output channel 8 |
| 19 | OUT7 | Output channel 7 |
| 20 | OUT6 | Output channel 6 |
| 21 | OUT5 | Output channel 5 |
| 22 | OUT4 | Output channel 4 |
| 23 | OUT3 | Output channel 3 |
| 24 | OUT2 | Output channel 2 |
|  | TP | TP Thermal-Pad |

The Thermal Pad is to be connected to a ground plane on the PCB. Connections between GND, GNDR and the ground plane should be conciled to system FMEA aspects.

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## ABSOLUTE MAXIMUM RATINGS

Beyond these values damage may occur; device operation is not guaranteed.

| Item No. | Symbol | Parameter | Conditions | Min. | Max. | Unit |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| G001 | VB, VBR | Supply Voltage |  | -0.3 | 40 | V |
| G002 | V() | Voltage at OUT1...8, NOK |  | -0.3 | 40 | V |
| G003 | V() | Voltage at IN1...8, EN5, EN10, ENFS |  | -0.3 | 40 | V |
| G004 | V(GNDR) | Voltage at GNDR referenced to GND |  | -0.3 | 0.3 | V |
| G005 | V(GND) | Voltage at GND referenced to GNDR |  | -0.3 | 0.3 | V |
| G006 | V(VBR) | Voltage at VBR referenced to VB |  | -0.3 | 0.3 | V |
| G007 | V(VB) | Voltage at VB referenced to VBR |  | -0.3 | 0.3 | V |
| G008 | $\operatorname{Imx}()$ | Current in OUT1...8, NOK, IN1...8, EN5, EN10, ENFS |  | -10 | 10 | mA |
| G009 | $\operatorname{lmx}()$ | Current in VB, VBR |  | -10 | 80 | mA |
| G010 | $\operatorname{Imx}()$ | Current in GND, GNDR |  | -80 | 10 | mA |
| G011 | Vd() | ESD susceptibility at all pins | HBM 100 pF discharged through $1.5 \mathrm{k} \Omega$ |  | 2 | kV |
| G012 | Tj | Operating Junction Temperature |  | -40 | 140 | ${ }^{\circ} \mathrm{C}$ |
| G013 | Ts | Storage Temperature Range |  | -55 | 125 | ${ }^{\circ} \mathrm{C}$ |

## THERMAL DATA

Operating Conditions: VB $=\mathrm{VBR}=4.5 \ldots 40 \mathrm{~V}, \mathrm{GND}=\mathrm{GNDR}=0 \mathrm{~V}$

| Item <br> No. | Symbol | Parameter | Conditions | Min. | Typ. |
| :--- | :--- | :--- | :--- | :---: | :---: | Max. | ${ }^{\circ} \mathrm{C}$ |  |
| :---: | :---: |
| T01 | Ta |
| T02 | Rthja |

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## ELECTRICAL CHARACTERISTICS

Operating Conditions: VB $=\mathrm{VBR}=4.5 \ldots 40 \mathrm{~V}, \mathrm{GND}=\mathrm{GNDR}=0 \mathrm{~V}, \mathrm{Tj}=-40 \ldots 125^{\circ} \mathrm{C}$ unless otherwise stated

| Item No. | Symbol | Parameter | Conditions | $\begin{aligned} & \hline \hline \mathrm{Tj} \\ & { }^{\circ} \mathrm{C} \end{aligned}$ | Fig. | Min. | Typ. | Max. | Unit |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Total Device |  |  |  |  |  |  |  |  |  |
| 001 | VB | Permissible Supply Voltage |  |  |  | 4.5 |  | 40 | V |
| 002 | I(VB) | Supply Current in VB | No load, EN5 = lo,EN10 = lo, ENFS = lo |  |  | 1.2 |  | 3.6 | mA |
| 003 | I(VB) | Supply Current in VB | No load, EN5 = hi,EN10 = lo, ENFS = lo, IN1. . $8=\mathrm{hi}$, $\mathrm{VB}=8 . .40 \mathrm{~V}$ |  |  | 3.2 |  | 6.6 | mA |
| 004 | I(VB) | Supply Current in VB | No load, EN5 = lo, EN10 = hi, ENFS = lo, IN1. . $8=\mathrm{hi}$, $V B=13 . .40 \mathrm{~V}$ |  |  | 3.2 |  | 6.8 | mA |
| 005 | I(VB) | Supply Current in VB | No load, EN5 = lo, EN10 = lo, ENFS = hi, IN1 $\ldots 8=\mathrm{hi}$, $\mathrm{VB}=4.5 \ldots 40 \mathrm{~V}$ |  |  | 1.3 |  | 6.6 | mA |
| 006 | I(VBR) | Supply Current in VBR |  |  |  |  | tbd |  | mA |
| 007 | I(GND) | Current in GND | No load |  |  | -7 |  |  | mA |
| 008 | I(GNDR) | Current in GNDR | No load, all OUTx = hi |  |  |  | tbd |  | mA |
| Current Driver OUT1... 8 |  |  |  |  |  |  |  |  |  |
| 101 | $\mathrm{Vc}(\mathrm{OUTx}) \mathrm{hi}$ | Clamp Voltage hi | l()$=10 \mathrm{~mA}$ |  |  | 42 |  | 60 | V |
| 102 | Vc(OUTx)Io | Clamp Voltage lo referenced to the lower voltage of GND, GNDR | I()$=-10 \mathrm{~mA}$ |  |  | -2 |  | -0.4 | V |
| 103 | Vs(OUTx)hi | Saturation Voltage hi referenced to VB | $\begin{aligned} & \mathrm{Vs}() \mathrm{hi}=\mathrm{VB}-\mathrm{V}(), \mathrm{INx}=\mathrm{hi}, \\ & \mathrm{ENFS}=\mathrm{hi} ; \\ & \mathrm{l}()=-0.5 \mathrm{~mA} \\ & \mathrm{l}()=-2 \mathrm{~mA} \end{aligned}$ |  |  |  |  | $\begin{aligned} & 0.2 \\ & 0.8 \end{aligned}$ | $\begin{aligned} & \mathrm{V} \\ & \mathrm{~V} \end{aligned}$ |
| 104 | Vs(OUTx)Io | Saturation Voltage lo referenced to GND | $\begin{aligned} & \mathrm{I}()=0.5 \mathrm{~mA} \\ & \mathrm{I}()=2 \mathrm{~mA} \end{aligned}$ |  |  |  |  | $\begin{aligned} & 0.2 \\ & 0.8 \end{aligned}$ | $\begin{aligned} & \mathrm{V} \\ & \mathrm{~V} \end{aligned}$ |
| 105 | Vr(OUTx) | Output Voltage regulated, no load | $\begin{aligned} & \text { EN5 = hi, INx }=\text { hi, } \\ & \mathrm{l}()=0 \mathrm{~mA} \end{aligned}$ |  |  | 4.7 | 5 | 5.3 | V |
| 106 | Vr (OUTx) | Output Voltage regulated, no load | $\begin{aligned} & \text { EN10 = hi, IN } x=h i, \\ & \mathrm{l}()=0 \mathrm{~mA} \end{aligned}$ |  |  | 9.4 | 10 | 10.6 | V |
| 107 | Ri(OUTx) | Output Resistance | $\begin{aligned} & \text { EN10 }=\text { hi or EN5 }=\text { hi, } \mathrm{INx}=\mathrm{hi} \\ & \mathrm{I}()= \pm 2 \mathrm{~mA} \end{aligned}$ |  |  | 100 |  | 500 | $\Omega$ |
| 108 | $\mathrm{VI}(\mathrm{OUTx})$ | Output Voltage | I (OUTx) $=2 \mu \mathrm{~A}$, GND open |  |  |  |  | 600 | mV |
| 109 | $\operatorname{lpd}(O U T x)$ | Pull-Down Current | $V(O U T x)=1 \mathrm{~V}$, GND open |  |  | 30 |  | 120 | $\mu \mathrm{A}$ |
| 110 | Rpd(OUTx) | Pull-Down Resistor at OUTx referenced to GNDR | VB, VBR, $\mathrm{V}(\mathrm{OUTX})=10 \mathrm{~V}$, GND open |  |  | 50 |  | 300 | k $\Omega$ |
| 111 | Rpd(OUTx) | Pull-Down Resistor at OUTx referenced to GNDR | VB, VBR, V(OUTX) $=40 \mathrm{~V}$, GND open |  |  | 100 |  | 600 | k $\Omega$ |
| 112 | Isc(OUTx)lo | Short circuit current lo | V()$=0.8 \mathrm{~V}$...VB |  |  | 2 | 3.6 | 10 | mA |
| 113 | Isc(OUTx)hi | Short circuit current hi | V()$=0 \ldots \mathrm{VB}-0.8 \mathrm{~V}$ |  |  | -10 | -3 | -2 | mA |
| 114 | Vsh(OUTx) | Output Voltage at short circuit of two outputs | EN5 = hi, <br> At two different input signals hi and lo |  |  |  |  | 1 | V |
| 115 | Vsh(OUTx) | Output Voltage at short circuit of two outputs | EN10 = hi oder ENFS = hi, At two different input signals hi and lo |  |  |  |  | 1.3 | V |
| 116 | $\mathrm{Vt}($ OUTx)hi | Threshold Voltage hi monitoring comparator | $\begin{aligned} & \mathrm{Vt}()=\mathrm{Vr}()-\mathrm{V}() \text { or } \\ & \mathrm{Vt}()=\mathrm{VB}-\mathrm{V}() \end{aligned}$ |  |  | 0.8 |  |  | V |
| 117 | Vt(OUTx)lo | Threshold Voltage lo monitoring comparator | $\begin{aligned} & \mathrm{Vt}()=\mathrm{Vr}()-\mathrm{V}() \text { or } \\ & \mathrm{Vt}()=\mathrm{VB}-\mathrm{V}() \end{aligned}$ |  |  |  |  | 2.2 | V |
| 118 | Vt()hys | Hysteresis | Vt() $\mathrm{hys}=\mathrm{Vt}() \mathrm{lo}-\mathrm{Vt}() \mathrm{hi}$ |  |  | 50 |  | 300 | mV |

## iC-MFN <br> 8-FOLD FAIL-SAFE N-FET DRIVER

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## ELECTRICAL CHARACTERISTICS

Operating Conditions: VB $=\mathrm{VBR}=4.5 \ldots 40 \mathrm{~V}, \mathrm{GND}=\mathrm{GNDR}=0 \mathrm{~V}, \mathrm{Tj}=-40 \ldots 125^{\circ} \mathrm{C}$ unless otherwise stated

| Item No. | Symbol | Parameter | Conditions | $\begin{aligned} & \hline \mathrm{Tj} \\ & { }^{\circ} \mathrm{C} \end{aligned}$ | Fig. | Min. | Typ. | Max. | Unit |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Input IN1...8, EN5, EN10, ENFS |  |  |  |  |  |  |  |  |  |
| 201 | Vc() hi | Clamp Voltage hi | l()$=10 \mathrm{~mA}$ |  |  | 42 |  | 60 | V |
| 202 | Vc() lo | Clamp Voltage lo referenced to the lower voltage of GND, GNDR | I()$=-10 \mathrm{~mA}$ |  |  | -2 |  | -0.4 | V |
| 203 | Vt() hi | Threshold Voltage hi |  |  |  | 1.15 |  | 1.4 | V |
| 204 | Vt() lo | Threshold Voltage lo |  |  |  | 0.8 |  | 1.05 | V |
| 205 | $\mathrm{Vt}($ )hys | Input Hysteresis | Vt() $\mathrm{hys}=\mathrm{Vt}() \mathrm{hi}-\mathrm{Vt}() \mathrm{lo}$ |  |  | 200 |  | 400 | mV |
| 206 | Ipd1() | Pull-Down Current 1 | $0.4 \mathrm{~V}<\mathrm{V}()<\mathrm{Vt}() \mathrm{hi}$ |  | 5 | 75 | 225 | 350 | $\mu \mathrm{A}$ |
| 207 | lpd2() | Pull-Down Current 2 | V()$>1.4 \mathrm{~V}$ |  | 5 | 20 | 45 | 70 | $\mu \mathrm{A}$ |
| 208 | Cin() | Input Capacitance |  |  |  |  |  | 20 | pF |
| 209 | I() | Leakage Current | $\mathrm{VB}, \mathrm{VBR}=0 \mathrm{~V}, \mathrm{~V}()=0 . .40 \mathrm{~V}$ |  |  | -10 |  | 10 | $\mu \mathrm{A}$ |
| Supply and Temperature Monitor |  |  |  |  |  |  |  |  |  |
| 301 | VBon | Turn-On Threshold VB |  |  |  | 3.8 |  | 4.3 | V |
| 302 | VBoff | Turn-Off Threshold VB | Decreasing voltage VB |  |  | 3.4 |  | 4.0 | V |
| 303 | VBhys | Hysteresis | VBhys = VBon - VBoff |  |  | 200 |  |  | mV |
| 304 | Toff | Turn-Off Temperature | Increasing temperature |  |  | 145 | 160 | 180 | ${ }^{\circ} \mathrm{C}$ |
| 305 | Ton | Turn-On temperature | Decreasing temperature |  |  | 130 | 147 | 170 | ${ }^{\circ} \mathrm{C}$ |
| 306 | Thys | Hysteresis | Thys = Toff - Ton |  |  |  | 13 |  | ${ }^{\circ} \mathrm{C}$ |
| Ground Monitor GND, GNDR |  |  |  |  |  |  |  |  |  |
| 401 | Vt() hi | Threshold Voltage hi GND Monitor | Referenced to GNDR |  |  |  |  | 270 | mV |
| 402 | Vt()lo | Threshold Voltage lo GND Monitor | Referenced to GNDR |  |  | 50 |  |  | mV |
| 403 | Vt()hys | Hysteresis | Vt() hys $=\mathrm{Vt}() \mathrm{hi}-\mathrm{Vt}() \mathrm{lo}$ |  |  | 5 |  | 100 | mV |
| 404 | Vt() hi | Threshold Voltage hi GNDR Monitor | Referenced to GND |  |  |  |  | 270 | mV |
| 405 | Vt()lo | Threshold Voltage lo GNDR Monitor | Referenced to GND |  |  | 50 |  |  | mV |
| 406 | Vt()hys | Hysteresis | Vt() hys $=\mathrm{Vt}() \mathrm{hi}-\mathrm{Vt}() \mathrm{lo}$ |  |  | 5 |  | 100 | mV |
| 407 | Vc() hi | Clamp Voltage GNDR hi referenced to GND | l()$=1 \mathrm{~mA}$ |  |  | 0.4 |  | 2 | V |
| 408 | Vc() lo | Clamp Voltage GNDR Io referenced to GND | l()$=-1 \mathrm{~mA}$ |  |  | -2 |  | -0.4 | V |
| Status Output NOK |  |  |  |  |  |  |  |  |  |
| 501 | Vc (NOK)hi | Clamp Voltage hi | 1()$=10 \mathrm{~mA}$ |  |  | 42 |  | 60 | V |
| 502 | Vc (NOK)lo | Clamp Voltage lo referenced to the lower voltage of GND, GNDR | l()$=-10 \mathrm{~mA}$ |  |  | -2 |  | -0.4 | V |
| 503 | $\mathrm{II}(\mathrm{NOK})$ | Leakage Current | GND < V $($ NOK $)<\mathrm{VB}$ |  |  | -20 |  | 20 | $\mu \mathrm{A}$ |
| 504 | Vs(NOK)lo | Saturation Voltage lo referenced to GND | $\begin{aligned} & \mathrm{I}()=0.5 \mathrm{~mA} \\ & \mathrm{I}()=2 \mathrm{~mA} \end{aligned}$ |  |  |  |  | $\begin{aligned} & 0.2 \\ & 0.8 \end{aligned}$ | $\begin{aligned} & \mathrm{V} \\ & \mathrm{~V} \end{aligned}$ |
| 505 | Isc(NOK)lo | Short circuit current lo | V()$=0.8 \mathrm{~V}$...VB |  |  | 2 | 3 | 10 | mA |
| Supply Monitor VB, VBR |  |  |  |  |  |  |  |  |  |
| 601 | Vt (VB) hi | Threshold Voltage hi VB Monitor | Referenced to VBR |  |  |  |  | 270 | mV |
| 602 | Vt(VB)lo | Threshold Voltage lo VB Monitor | Referenced to VBR |  |  | 50 |  |  | mV |
| 603 | Vt(VB)hys | Hysteresis | Vt() hys $=\mathrm{Vt}() \mathrm{hi}-\mathrm{Vt}() \mathrm{lo}$ |  |  | 5 |  | 100 | mV |
| 604 | Vt(VBR)hi | Threshold Voltage hi VBR Monitor | Referenced to VB |  |  |  |  | 270 | mV |
| 605 | Vt(VBR)lo | Threshold Voltage lo VBR Monitor | Referenced to VB |  |  | 50 |  |  |  |
| 606 | Vt(VBR)hys | Hysteresis | Vt() $\mathrm{hys}=\mathrm{Vt}() \mathrm{hi}-\mathrm{Vt}() \mathrm{lo}$ |  |  | 5 |  | 100 | mV |
| 607 | $\mathrm{Vc}(\mathrm{VBR}) \mathrm{hi}$ | Clamp Voltage hi | l()$=1 \mathrm{~mA}, \mathrm{Vc}()=\mathrm{V}(\mathrm{VBR})-\mathrm{V}(\mathrm{VB})$ |  |  | 0.4 |  | 2 | V |
| 608 | $\mathrm{Vc}(\mathrm{VBR}) \mathrm{lo}$ | Clamp Voltage lo | $\begin{aligned} & \mathrm{l}()=-1 \mathrm{~mA}, \mathrm{Vc}()=\mathrm{V}(\mathrm{VBR})- \\ & \mathrm{V}(\mathrm{VB}) \end{aligned}$ |  |  | -2 |  | -0.4 | V |

8-FOLD FAIL-SAFE N-FET DRIVER

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## ELECTRICAL CHARACTERISTICS

Operating Conditions: VB $=\mathrm{VBR}=4.5 \ldots 40 \mathrm{~V}, \mathrm{GND}=\mathrm{GNDR}=0 \mathrm{~V}, \mathrm{Tj}=-40 \ldots 125^{\circ} \mathrm{C}$ unless otherwise stated

| Item No. | Symbol | Parameter | Conditions | $\begin{aligned} & \hline \mathrm{Tj} \\ & { }^{\circ} \mathrm{C} \end{aligned}$ | Fig. | Min. | Typ. | Max. | Unit |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Testmode EN5, EN10, ENFS |  |  |  |  |  |  |  |  |  |
| 701 | Vt() hi | Threshold Voltage hi disable test | EN5 = EN10 = ENFS |  |  |  |  | -60 | mV |
| 702 | $\mathrm{Vt}($ ) lo | Threshold Voltage lo enable test | EN5 = EN10 = ENFS |  |  | -320 |  |  | mV |
| 703 | $\mathrm{Vt}($ ) hys | Hysteresis | Vt()hys = Vt () hi - Vt() lo |  |  | 50 |  | 160 | mV |
| Timing |  |  |  |  |  |  |  |  |  |
| 901 | $\operatorname{tp}(\mathrm{OUTx})$ | Propagation delay INx, EN5 $\rightarrow$ OUTx | (\{INx,EN5\}lo $\rightarrow$ hi) $\rightarrow 90 \%$ OUTx (\{INx,EN5\}hi $\rightarrow$ lo) $\rightarrow 10$ \%OUTx CLoad() $=100 \mathrm{pF}$ |  | 1 | 0.45 |  | 1.1 | $\mu \mathrm{s}$ |
| 902 | tp(OUTx) | Propagation delay INx, EN5 $\rightarrow$ OUTx | (\{INx,EN5\}lo $\rightarrow$ hi) $\rightarrow 90 \% O U T x$ (\{INx,EN5\}hi $\rightarrow$ lo) $\rightarrow 10$ \%OUTx CLoad() $=1 \mathrm{nF}$ |  | 1 | 1.3 |  | 2.4 | $\mu \mathrm{s}$ |
| 903 | tp(OUTx) | Propagation delay INx, EN5 $\rightarrow$ OUTx | (\{INx,EN5\}lo $\rightarrow$ hi) $\rightarrow 90 \% O U T x$ (\{INx,EN5\}hi $\rightarrow$ lo) $\rightarrow 10$ \%OUTx CLoad () $=2 \mathrm{nF}$ |  | 1 | 2.2 |  | 3.7 | $\mu \mathrm{s}$ |
| 904 | tp(OUTx) | Propagation delay INx, EN5 $\rightarrow$ OUTx | (\{INx,EN5\}lo $\rightarrow$ hi) $\rightarrow 90$ \%OUTx (\{INx,EN5\}hi $\rightarrow$ lo) $\rightarrow 10$ \%OUTx CLoad() $=5 \mathrm{nF}$ |  | 1 | 5 |  | 8.1 | $\mu \mathrm{s}$ |
| 905 | tp(OUTx) | Propagation delay INx, EN10 $\rightarrow$ OUTx | (\{INx,EN10\}lo $\rightarrow$ hi) $\rightarrow 90 \%$ OUTx (\{INx,EN10\}hi $\rightarrow$ Io) $\rightarrow 10$ \%OUTx CLoad() $=100 \mathrm{pF}$ |  | 1 | 0.7 |  | 1.6 | $\mu \mathrm{s}$ |
| 906 | tp(OUTx) | Propagation delay INx, EN10 $\rightarrow$ OUTx | (\{INx,EN10\}lo $\rightarrow$ hi) $\rightarrow 90 \%$ OUTx (\{INx,EN10\}hi $\rightarrow$ lo) $\rightarrow 10$ \%OUTx CLoad() $=1 \mathrm{nF}$ |  | 1 | 2.3 |  | 4.1 | $\mu \mathrm{s}$ |
| 907 | tp(OUTx) | Propagation delay INx, EN10 $\rightarrow$ OUTx | (\{INx,EN10\}lo $\rightarrow$ hi) $\rightarrow 90 \%$ OUTx (\{INx,EN10\}hi $\rightarrow \mathrm{lo}$ ) $\rightarrow 10$ \%OUTx CLoad() $=2 \mathrm{nF}$ |  | 1 | 3.9 |  | 7.1 | $\mu \mathrm{s}$ |
| 908 | tp(OUTx) | Propagation delay INx, EN10 $\rightarrow$ OUTx | (\{INx,EN10\}lo $\rightarrow$ hi) $\rightarrow 90 \%$ OUTx (\{INx,EN10\}hi $\rightarrow$ lo) $\rightarrow 10$ \%OUTx CLoad() $=5 \mathrm{nF}$ |  | 1 | 9 |  | 16 | $\mu \mathrm{s}$ |
| 909 | tp(OUTx) | Propagation delay INx, ENFS $\rightarrow$ OUTx | $\begin{aligned} & (\{I N x, \text { ENFS }\} / \mathrm{lo} \rightarrow \mathrm{hi}) \rightarrow 90 \% \text { OUTx } \\ & (\{I N x, \text { ENFS }\} \mathrm{hi} \rightarrow \mathrm{lo}) \rightarrow 10 \% \text { OUTx } \\ & \text { CLoad }()=100 \mathrm{pF} \end{aligned}$ |  | 1 | 1.4 |  | 3.1 | $\mu \mathrm{s}$ |
| 910 | tp(OUTx) | Propagation delay INx, ENFS $\rightarrow$ OUTx | (\{INx,ENFS\}lo $\rightarrow$ hi) $\rightarrow 90$ \%OUTx (\{INx,ENFS\}hi $\rightarrow$ lo) $\rightarrow 10$ \%OUTx CLoad() $=1 \mathrm{nF}$ |  | 1 | 5.2 |  | 9.8 | $\mu \mathrm{s}$ |
| 911 | tp(OUTx) | Propagation delay INx, ENFS $\rightarrow$ OUTx | (\{INx,ENFS\}lo $\rightarrow$ hi) $\rightarrow 90$ \%OUTx (\{INx,ENFS\}hi $\rightarrow$ lo) $\rightarrow 10$ \%OUTx CLoad() $=2 \mathrm{nF}$ |  | 1 | 9.2 |  | 16.7 | $\mu \mathrm{s}$ |
| 912 | tp(OUTx) | Propagation delay INx, ENFS $\rightarrow$ OUTx | (\{INx,ENFS\}lo $\rightarrow$ hi) $\rightarrow 90$ \%OUTx (\{INx,ENFS\}hi $\rightarrow$ lo) $\rightarrow 10$ \%OUTx CLoad() $=5 \mathrm{nF}$ |  | 1 | 20 |  | 35 | $\mu \mathrm{s}$ |
| 913 | dV()$/ \mathrm{dt}$ | Slew rate | $\mathrm{VB}=24 \mathrm{~V}, \mathrm{CLoad}()=100 \mathrm{pF}$ |  |  | 7 |  | 18 | $\mathrm{V} / \mu \mathrm{s}$ |
| 914 | dV()$/ \mathrm{dt}$ | Slew rate | $\mathrm{VB}=24 \mathrm{~V}, \mathrm{CLoad}()=1 \mathrm{nF}$ |  |  | 2.2 |  | 4.5 | $\mathrm{V} / \mu \mathrm{s}$ |
| 915 | $\mathrm{dV}(\mathrm{)} / \mathrm{dt}$ | Slew rate | $\mathrm{VB}=24 \mathrm{~V}, \mathrm{CLoad}()=2 \mathrm{nF}$ |  |  | 1.2 |  | 2.5 | $\mathrm{V} / \mu \mathrm{s}$ |
| 916 | $\mathrm{dV}(\mathrm{)} / \mathrm{dt}$ | Slew rate | $\mathrm{VB}=24 \mathrm{~V}, \mathrm{CLoad}()=5 \mathrm{nF}$ |  |  | 0.5 |  | 1.2 | $\mathrm{V} / \mu \mathrm{s}$ |

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ELECTRICAL CHARACTERISTICS: Diagrams


Figure 1: Propagation delays

## iC-MFN

8-FOLD FAIL-SAFE N-FET DRIVER

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## DESCRIPTION OF FUNCTIONS

## Hi-level output configuration

The device iC-MFN has three adjustable hi-levels for driving N -channel fets. The configured hi-level is common to all outputs OUTx and the maxmimum level is the power supply VB potential. The hi-level configuration inputs are used simultaneous for enabling the hilevel at the outputs OUTx. The hi-level at exactly one input EN5, EN10 or ENFS configure the voltage of hilevel and enable the outputs. If more than one of these inputs have hi-level the outputs remains disabled. The hi-level 5 V (configured with EN5 = hi) and 10 V (configured with EN10 = hi) are internally generated by a voltage reference and regulated. The hi-level VB (configured with ENFS = hi) is an unregulated connection to VB. In this case the voltage swing depends directly from the power supply VB.

## Output characteristics of the highside transistor

The highside output transistors at the eight channels demonstrate a resistive behavior with low voltage (VB $-\mathrm{V}(\mathrm{OUTx})$ ) and behave as a current source with finite output resistance with higher voltages.


Figure 2: Output characteristic of the highside transistor at OUTx


Figure 3: Output characteristic of the regulated push-pull-output at OUTx

## Output characteristic of the lowside transistor

The lowside output transistors at the eight channels demonstrate a resistive behavior with low voltage V (OUTx) and behave as a current sink with finite output resistance with higher voltages.


Figure 4: Output characteristic of the lowside transistor at OUTx

## Status output NOK

The status output NOK is a current limited 40 V proof open-drain output. The output transistor is switched on if the hi-level of the outputs OUTx are enabled with exactly one pin ENx, the outputs have reached the voltage levels defined by the inputs INx, the power supply voltage is above the power-on threshold, the temperature is below the switch off temperature and all power supply pins are connected.

## Output characteristic of the regulated push-pulloutput at OUTx

The hi-level 5 V and 10 V is generated with a regulated push-pull output and demonstrate a resistive behavior with low voltage changes and behave as a current source with finite output resistance with higher voltage changes.

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## Pull-down currents

In order to enhance noise immunity with limited power dissipation at inputs INx, EN5, EN10 and ENFS the pull-down currents at these pins have two stages. With a rise in voltage at input pins INx, EN5, EN10 und ENFS the pull-down current remains high until Vt()hi (Electrical Characteristics No. 203); above this threshold the device switches to a lower pull-down current. If the voltage falls below $\mathrm{Vt}($ ) lo (Electrical Characteristics No. 204), the device switches back to a higher pull-down current.


Figure 5: Pull-down currents at INx, EN5, EN10 and ENFS

## DETECTING SINGLE ERRORS

If single errors are detected, safety-relevant applications require externally connected switching transistors to be specifically shut down. Single errors can occur when a pin is open (due to a disconnected bonding wire or a bad solder connection, for example) or when two pins are short-circuited.

When two output of different logic levels are shortcircuited, the driving capability of the lowside driver will predominate, keeping the connected N -channel FETs in a safe shutdown state.

With open pins VB, VBR, GND or GNDR iC-MFN switches the output stages to a safe, predefined low state via pull-down resistors and current sources at the outputs, subsequently shutting down any externally connected N -channel FETs.

## Loss of VB potential

If power supply potential is no longer applied to the VBpin, the output stage highside drivers are shut down and the outputs actively tied to GND via the lowside drivers.

## Loss of VBR potential

If power supply potential is no longer applied to the VBR-pin, the output stage highside drivers are shut down and the outputs actively tied to GND via the lowside drivers.

## Loss of GNDR potential

If ground potential is no longer applied to the GNDRpin, the output stage highside drivers are shut down and the outputs actively tied to GND via the lowside drivers.


Figure 6: Output characeristics at OUTx with loss of VB, VBR or GNDR

## Loss of GND potential

If ground potential is not longer applied to GND, the output stages are shut down and the outputs tied to GNDR via current sources and internal pull-down resistors with a typical value of $200 \mathrm{k} \Omega$.


Figure 7: Output characeristics at OUTx with loss of GND

## iC-MFN

## APPLICATION NOTES

## Driving an N-channel MOSFET

One typical field of application for iC-MFN is in the operation of N-FETs with microprocessor output signals, as shown in Figure 8.


Figure 8: Driving an N -channel MOSFET

Slowly switching of a transistor is done with a current limited driver. Figure 9 shows the different phases of a turn on process with resitive load. In Section t0 to t 1 the gate of the transistors is loaded to the threshold voltage Vth(FET) and is a dead time. In section t1 to t2 the gate voltage keeps nearly constant (miller-plateau) during the drain voltage slope. The slew rate depends on the current of the driver and the gate-drain capacitor of the transistor. In section t2 to t3 the gate voltage reach the static value. The transistor thus goes low ohmic and minimizes the power dissipation. The equations 1 to 4 are simplified and give an estimation of the timing on the basis of data from the specifications of the device iC-MFN and the used transistor. The turn off looks similar to the turn on but with reverse run trough.


Figure 9: On switching of a transistor

$$
\begin{equation*}
t_{t 0 . . t 1}[\mu s]=C_{i s s} @\left(V_{d s}=h i\right) \times \frac{V_{t h}(F E T)}{-I s c(O U T x) h i} \tag{1}
\end{equation*}
$$

$$
\begin{gather*}
t_{t 1 . . t 2}[\mu s]=C_{\mathrm{rss}} @\left(V_{d s}=h i\right) \times \frac{V B}{-\operatorname{Isc}(O U T x) h i}  \tag{2}\\
t_{t 2 . . t 3}[\mu s]=C_{i s s} @\left(V_{d s}=l o\right) \times \frac{V r(O U T x)-V_{t h}(F E T)}{-I s c(O U T x) h i} \tag{3}
\end{gather*}
$$

$$
\begin{equation*}
t_{o n}=t_{t 0 . . t 1}+t_{t 1 . . t 2}+t_{t 2 . . t 3} \tag{4}
\end{equation*}
$$

$C_{\text {iss }}=C_{g s}+C_{g d}=$ voltage dependent gate-source and gate-drain capacitor [ nF ]
$C_{\text {rss }}=C_{g d}=$ voltage dependent gate-drain capacitor [ nF ]
Isc(OUTx)lo = short circuit current lo at OUTx [mA]
$t_{t 0 . . t 1}=$ dead time $[\mu \mathrm{s}]$
$t_{t 1 . . t 2}=$ slope time at drain (Miller-Plateau) [ $\left.\mu \mathrm{s}\right]$
$t_{t 2 . . t 3}=$ time to reach static gate voltage $[\mu \mathrm{s}]$
$t_{o n}=$ overall turn on time [ $\mu \mathrm{s}$ ]
$V B=$ power supply $\mathrm{VB}[\mathrm{V}$ ]
$\operatorname{Vr}(O U T x)=$ configured static turn on voltage at OUTx [V]
$V_{t h}(F E T)=$ threshold of the transistor [V]

[^0]\[

$$
\begin{aligned}
& \text { did } \\
& \text { or }
\end{aligned}
$$
\]


$\square$

## Example

Turn on calculation with following estimations:
$C_{\text {iss }} @\left(V_{d s}=24 \mathrm{~V}\right)=1.5 \mathrm{nF}$
$C_{i s s} @\left(V_{d s}=1 \mathrm{~V}\right)=3 \mathrm{nF}$
$C_{\text {rss }} @\left(V_{d s}=24 \mathrm{~V}\right)=0.3 \mathrm{nF}$
Isc(OUTx)hi $=-4 \mathrm{~mA}$
$V B=24 \mathrm{~V}$
$\operatorname{Vr}(O U T x)=10 \mathrm{~V}$
$V_{t h}(F E T)=3 \mathrm{~V}$
From this follows:
$t_{t 0 . . t 1}=1.13 \mu \mathrm{~s}$
$t_{t 1 . . t 2}=1.8 \mu \mathrm{~s}$
$t_{t 2 . . t 3}=5.25 \mu \mathrm{~s}$
$t_{o n}=8.18 \mu \mathrm{~s}$
The slew rate at the drain of transistor is: $13.3 \mathrm{~V} / \mu \mathrm{s}$

Figure 10 shows the turn on and off at one channel with pin INx. The pulse duration at pin NOK, especially at turn on, can be used for monitoring the connected transistor and the load.


Figure 10: Turn on and off one channel with INx


Figure 11: Circuit diagram one channel with monitoring comparator

[^1]
## ORDERING INFORMATION

| Type | Package | Order Designation |
| :--- | :--- | :--- |
| iC-MFN | QFN24 4 mm | iC-MFN QFN24 |

For technical support, information about prices and terms of delivery please contact:

## iC-Haus GmbH <br> Am Kuemmerling 18 <br> D-55294 Bodenheim GERMANY

Appointed local distributors: http://www.ichaus.de/support_distributors.php


[^0]:    

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